# Applications of the Extremogram to Time Series and Spatial Processes

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## **Extremes and Time Series Modeling**

Do fitted models actually capture the desired (*extremal*) characteristics of the data?

- How do we assess "fitted" (expected) with "observed"?
- Need a mechanism for measuring extremal dependence.

Goal of this talk: Describe the extremogram which may be useful as a tool for addressing this question. That is, how well does the "sample" extremogram match up with the "population" extremogram?

# Illustration (Windspeed at Kilkenny)





#### ACF Plots for Kilkenny

ACF of the from 15 simulated realizations from fitted AR model + real data.



#### ACF Plots for Kilkenny

ACF of the *squares* from 15 simulated realizations from fitted AR model + real data.



# Game Plan

#### Extremes and time series modeling

- A motivating example
- Starting point: GARCH vs SV
- The Extremogram
  - Examples
  - Sufficient conditions for existence: regular variation
  - Empirical extremogram
  - Illustrations (permutation procedures)
  - Cross-extremogram (devolatilizing/deGARCHing)
- Application to spatial processes
  - Kernel estimate of extremogram
  - Rainfall data

### Characteristics of financial time series

Define 
$$X_t = \ln (P_t) - \ln (P_{t-1})$$
 (log returns)

heavy tailed

$$\mathsf{P}(|\mathsf{X}_1| > \mathsf{x}) \sim \mathsf{RV}(-\alpha), \quad 0 < \alpha < 4.$$

uncorrelated

 $\hat{\rho}_X(h)$  near 0 for all lags h > 0

•  $|X_t|$  and  $X_t^2$  have slowly decaying autocorrelations

 $\hat{\rho}_{|X|}(h)$  and  $\hat{\rho}_{X^2}(h)$  converge to 0 *slowly* as h increases.

process exhibits 'volatility clustering'.

#### Example: Log returns for IBM 1/3/62-11/3/00



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# Starting point: GARCH vs SV

 $X_t = \sigma_t Z_t$  (observation eqn in state-space formulation) (i) GARCH(1,1)

$$X_{t} = \sigma_{t} Z_{t}, \quad \sigma_{t}^{2} = \alpha_{0} + \alpha_{1} X_{t-1}^{2} + \beta_{1} \sigma_{t-1}^{2}, \quad \{Z_{t}\} \sim \text{IID}(0,1)$$

(ii) Stochastic Volatility

$$X_t = \sigma_t Z_t$$
,  $\log \sigma_t^2 = \phi_0 + \phi_1 \log \sigma_{t-1}^2 + \varepsilon_t$ ,  $\{\varepsilon_t\} \sim \text{IIDN}(0, \sigma^2)$ 

Key question:

What intrinsic (extremal?) features in the data (*if any*) can be used to discriminate between these two models?

# The Extremogram

The extremogram of a stationary time series  ${X_t}$  can be viewed as the analogue of the correlogram in time series for measuring dependence in extremes (see Davis and Mikosch (2009)).

**Definition**: For two sets A & B **bounded away from 0**, the **extremogram** is defined as

 $\rho_{A,B}(h) = \lim_{x\to\infty} P(\mathbf{X}_h \in xB \mid \mathbf{X}_0 \in xA)$ 

=  $\lim_{x\to\infty} P(\mathbf{X}_0 \in xA, \mathbf{X}_h \in xB)/P(\mathbf{X}_0 \in xA),$ 

for h = 0, 1, ..., provided the limit exists, where  $X_h = (X_h, X_{h+1}, ..., X_{h+k})$ .

Remark: This definition requires that the limit exists.

- a) exists for heavy-tailed time series (see forthcoming slide)
- b) exists for some light-tailed time series w/ special choices of A and B.
- c) extremal dependence *depends* on the choice of sets A & B.

The Extremogram (cont)

If one takes  $A=B=(1,\infty)$  and k = 0, then

 $\rho_{\mathsf{A},\mathsf{B}}(\mathsf{h}) = \lim_{\mathsf{x}\to\infty} \mathsf{P}(\mathsf{X}_\mathsf{h} > \mathsf{x} \mid \mathsf{X}_\mathsf{0} > \mathsf{x}) = \lambda(\mathsf{X}_\mathsf{0},\mathsf{X}_\mathsf{h})$ 

often called the *extremal dependence coefficient* ( $\lambda = 0$  means independence or asymptotic independence).

Other choices of A and B can lead to interesting extremograms:

- $P(X_1 < -x | X_0 < -x)$  (negative return followed by a neg return)
- $P(X_1 > x | X_0 < -x)$  (neg return followed by a pos return)
- $P(X_1 + \cdots + X_4 > 2x | X_0 < -x)$  (neg return followed by a big pos

return aggregated over next 4 days)

•  $P(X_1 > x, ..., X_4 > x | X_0 > x)$  (pos return followed by a pos

return in next 4 days)

# The Extremogram: examples

Let  $A = B = (1,\infty)$ , then

$$\mathcal{P}_{A,B}(h) = \lim_{x \to \infty} P(X_0 > x, X_h > x) / P(X_0 > x)$$

Gaussian Processes: In this case,

 $\rho_{A,B}(h) = 0$  for all h > 0 (asymptotic independence).

connected to the Gaussian copula.

GARCH: In this case

 $\rho_{A,B}(h) > 0$  for all h > 0,

but decays to 0 geometrically fast.

SV process: 
$$X_t = \sigma_t Z_t$$
,  $\log \sigma_t^2 = \mu + \sum_{j=0}^{\infty} \psi_j \varepsilon_{t-j}$ ,  $\{\varepsilon_t\} \sim \text{IIDN}(0, \sigma^2)$   
In this case,

$$\rho_{A,B}(h) = 0$$
 for all  $h > 0$ .

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## The Extremogram: examples

Let  $A = B = (1,\infty)$ , then

$$\rho_{A,B}(h) = \lim_{x\to\infty} P(X_0 > x, X_h > x)/P(X_0 > x)$$

AR(1):  $X_t = \phi X_{t-1} + Z_t$ ,  $\{Z_t\}$ ~IID Cauchy. Then

 $\rho_{A,B}(h) = max(0, \phi^h).$ 

Note if  $\phi < 0$ , then extremogram alternates between positive #'s and 0

MaxMA(2): Let  $(Z_t)$  be iid with Pareto distribution, i.e.,  $P(Z_1 > x) = x^{-\alpha}$  for  $x \ge 1$ , and set  $X_t = max(Z_t, Z_{t-1}, Z_{t-2})$ . Then

$$\rho_{A,B}(h) = 1 \quad \text{for } h = 0.$$
  
= 2/3 for h = 1
  
= 1/3 for h = 2
  
= 0, for h > 2.

# Regular Variation — multivariate case

Regular variation of  $X=(X_1, \ldots, X_k)$ : (heavy-tailed analogue of multivariate Gaussian)

(i) The radial part |X| is heavy-tailed, i.e.,

 $\mathsf{P}(|\mathbf{X}| > tx)/\mathsf{P}(|\mathbf{X}| > t) \to x^{-\alpha}.$ 

(ii) The angular part X / |X| is asymptotically independent of the radial part |X|, i.e., there exists a random vector  $\theta \in S^{k-1}$  such that

$$\mathsf{P}(\mathbf{X}/|\mathbf{X}| \in \bullet \mid |\mathbf{X}| > t) \to_{\scriptscriptstyle W} \mathsf{P}(\theta \in \bullet) \quad \text{as } t \to \infty.$$

 $(\rightarrow_w \text{ weak convergence on } S^{k-1} = \text{ unit sphere in } R^k)$ .

- P( $\theta \in \bullet$ ) is called the spectral measure
- $\alpha$  is the index of **X**.

**Definition:** A time series  $\{X_t\}$  is *regularly varying* if all the finite dimensional distributions are regularly varying.

# Regular Variation and the Extremogram

#### Facts

- 1. The extremogram of a RV stationary time series  $\{X_t\}$  exists for all choices of sets A & B bounded away from the origin.
- 2. Many heavy-tailed time series (GARCH and SV) are regularly varying.

# The Empirical Extremogram

A natural estimator of the extremogram,

$$\rho_{A,B(h)} = \lim_{x \to \infty} P(X_h \in xB \mid X_0 \in xA)$$

based on observations,  $X_1, \ldots, X_n$ , is the empirical extremogram defined by

$$\hat{\rho}_{A,B}(h) = \frac{\frac{m}{n} \sum_{t=1}^{n-h} I_{\{a_m^{-1} X_t \in A, a_m^{-1} X_{t+h} \in B\}}}{\frac{m}{n} \sum_{t=1}^{n} I_{\{a_m^{-1} X_t \in A\}}},$$

where  $a_m$  is the 1 - 1/m quantile of  $|X_t|$ . For the theory to work, need

$$m_n \rightarrow \infty$$
 with  $m/n \rightarrow 0$ .

Under suitable mixing conditions, a CLT for the empirical estimate is established in D&M (2009).

The Empirical Extremogram — central limit theorem

$$\hat{\rho}_{A,B}(h) = \frac{\frac{m}{n} \sum_{t=1}^{n-h} I_{\{a_m^{-1} X_t \in A, a_m^{-1} X_{t+h} \in B\}}}{\frac{m}{n} \sum_{t=1}^{n} I_{\{a_m^{-1} X_t \in A\}}}$$

After first establishing a joint CLT for the numerator and denominator, we obtain the limit result

$$(n/m)^{1/2}(\hat{\rho}_{A,B}(h)-\rho_m(h))\rightarrow_d N(0,\sigma^2(A,B)),$$

where  $\rho_m(h)$  is the ratio of expectations (*pre-asymptotic extremogram*), P  $(a_m^{-1}X_0 \in A, a_m^{-1}X_h \in B)/P(a_m^{-1}X_0 \in A)$ .

Now provided a bias condition, such as

$$(n/m)^{1/2} \left( mP \left( a_m^{-1}X_0 \in A, a_m^{-1}X_h \in B \right) - \mu_h(A \times B) \right) \rightarrow 0,$$

holds, then  $\rho_m(h)$  can be replaced with  $\rho_{A,B}(h)$ . This condition can often be difficult to check.



Extremogram  $A=B=(1,\infty)$ 



Extremogram  $A=B=(1,\infty)$ 



Best fitting AR model is of order 18; refine with nonzero coefficients at lags 1, 2, 3, 5, 6, 7, 11, 13, 14, 16, and 18.

Extremogram  $A=B=(1,\infty)$ 



Best fitting AR model is of order 18; refine with nonzero coefficients at lags 1, 2, 3, 5, 6, 7, 11, 13, 14, 16, and 18.

## **Resampling and Testing for Serial Dependence**

A natural way (*not often used in time series*) for testing serial correlation is to compute the ACF for random permutations of the data. If the sample ACF appears more *extreme* than the ACFs based on random permutations, then there is evidence of serial correlation. We apply the same idea to the extremogram.



## **Resampling and Testing for Serial Dependence**

A natural way (*not often used in time series*) for testing serial correlation is to compute the ACF for random permutations of the data. If the sample ACF appears more *extreme* than the ACFs based on random permutations, then there is evidence of serial correlation. We apply the same idea to the extremogram.



Extremogram for residuals from subset AR(18) and from GARCH  $A=B=(1,\infty)$ 



Extremogram for residuals from subset AR(18) and from GARCH A=B= $(1,\infty)$ 







# Extremogram for FTSE, S&P, DAX, Nikkei



# Extremogram for FTSE, S&P, DAX, Nikkei



# Cross-Extremogram FTSE and SP



## **Cross-Extremogram**

**Strategy**: Devolatilize the component series before computing the extremogram. This is *analogous* to the issue of spurious cross-correlations in a time series without whitening the series first.

Cross-correlation between two "independent" AR(1)'s Cross-correlation between the *whitened* series'





Devolatilizing (deGARCHing) S&P

Extremogram for S&P: significant for large number of lags ~40+

Devolatilize S&P by fitting GARCH(1,1):  $X_t = (6.28e - 7 + .057X_{t-1}^2 + .939\sigma_{t-1}^2)^{1/2}Z_t,$  $\{Z_t\} \sim IID \ t(6.14),$ 



## Devolatilizing S&P

Extremogram for S&P: significant for large number of lags ~40+







# Extremogram in Space

Setup: Let X(s) be a stationary (isotropic?) spatial process defined on  $s \in \mathbb{R}^2$  (or on a regular lattice  $s \in \mathbb{Z}^2$ ).



## Extremal Dependence in Space and Time



## Space-time domain: $\{(\boldsymbol{s}, t) \in \mathbb{R}^d \times [0, \infty)\}$

## Illustration with French Precipitation Data

Data from Naveau et al. (2009). Precipitation in Bourgogne of France; 51 year maxima of daily precipitation. Data has been adjusted for seasonality and orographic effects.



#### Lattice vs cont space

Setup: Let X(s) be a RV stationary (isotropic?) spatial process defined on  $s \in \mathbb{R}^2$  (or on a regular lattice  $s \in \mathbb{Z}^2$ ). Consider the former—latter is more straightforward.

$$\rho_{A,B}(h) = \lim_{x \to \infty} P(X(s+h) \in xB \mid X(s) \in xA), \qquad h \in \mathbb{R}^2$$

regular grid

#### random pattern



# **France Precipitation Data**

#### regular or random?



## Random pattern

#### random pattern



## Random pattern

#### random pattern



Note:

- Expanding domain asymptotics: domain is getting bigger.
- Not infill asymptotics: insert more points in fixed domain.

#### Estimating the extremogram--random pattern

Setup: Suppose we have observations,  $X(s_1), ..., X(s_N)$  at locations  $s_1, ..., s_{N_n}$  of some Poisson process N with rate v in a domain  $S_n \uparrow \mathbb{R}^2$ . Here,  $N_n = N(S_n) =$  number of Poisson points in  $S_n$ ,  $N_n \sim Pois(v|S_n|)$ . Weight function  $w_n(x)$ : Let  $w(\cdot)$  be a bounded pdf and set

$$w_n(x) = \frac{1}{\lambda_n^2} w\left(\frac{x}{\lambda_n}\right),$$

where the bandwidth  $\lambda_n \to 0$  and  $\lambda_n^2 |S_n| \to \infty$ .

## Estimating extremogram--random pattern

$$\rho_{A,B}(h) = \lim_{x \to \infty} P(X(s+h) \in xB, X(s) \in xA) / P(X(s) \in xA), \qquad h \in \mathbb{R}^2$$

#### Kernel estimate of $\rho$ :

 $\hat{\rho}_{A,B}(h) =$ 

$$\frac{m_n}{\nu^2 |S_n|} \int_{S_n} \int_{S_n} w_n(h+s_1-s_2) I(X(s_1) \in a_m B) I(X(s_2) \in a_m A) N^2(ds_1, ds_2)$$
$$\frac{m_n}{\nu |S_n|} \int_{S_n} I(X(s) \in a_m A) N(ds)$$

Note:  $N^2(ds_1, ds_2) = N(ds_1)N(ds_2)I(s_1 \neq s_2)$  is product measure off the diagonal.

Limit theory:

$$\left(\frac{|S_n|\lambda_n^2}{m_n}\right)^{\frac{1}{2}} \left(\hat{\rho}_{A,B}(h) - \rho_{A,B,m}(h)\right) \to N(0,\Sigma),$$

Simulation of spatial extremogram

#### Box-plots based on 100 replications of BR on nonlattice

 $\lambda_n = 1/\log n$  (left),  $\lambda_n = 5/\log n$  (right)





Radar data:

Rainfall in inches measured in 15-minutes intervals at points of a spatial 2x2km grid.

**Region:** 

120x120km, results in 60x60=3600 measurement points in space.

Take only wet season (June-September).

Block maxima in space: Subdivide in 10x10km squares, take maxima of rainfall over 25 locations in each square. This results in 12x12=144 spatial maxima.

Temporal domain: Analyze daily maxima and hourly accumulated rainfall observations.

Fit our extremal space-time model to daily/hourly maxima.

Hourly accumulated rainfall fields for four time points.



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2.0

- 1.5

1.0

0.5

0.0

2.0

- 1.5

- 1.0

0.5

0.0

Empirical extremogram in space (left) and time (right)

Spatial extremogram

Temporal extremogram





Empirical extremogram in space (left) and time (right): spatial indep for lags > 4; temporal indep for lags > 6.



Computing conditional return maps.

Estimate  $z_c(s, t)$  such that

$$P(Z(s,t) > z_c(s,t) \mid Z(s^*,t^*) > z^*) = p_c,$$

where  $z^*$  satisfies  $P(Z(s^*, t^*) > z^*) = p^*$  is pre-assigned.

A straightforward calculation shows that  $z_c(s, t)$  must solve,

$$p_{c} = 1 - \frac{1}{p^{*}} \exp\left\{-\frac{1}{z_{c}(s,t)}\right\} + \frac{1}{p^{*}} F_{(BR)}(z_{c}(s,t), 1-p^{*}),$$

100-hour return maps ( $p_c = .01$ ):  $s^* = (5,6)$ , time lags = 0,2,4,6 hours (left to right on top and then right to left on bottom), quantiles in inches.



• *Extremogram* is another potential tool for estimating extremal dependence that may be helpful for discriminating between models on the basis of extreme value behavior.

• Permutation procedures are a *quick* and *clean* way to test for significant values in the extremogram and other statistics.

• *Bootstrapping* may prove useful for constructing Cl's for the extremogram and also for assessing extremal dependence.

• The *Extremogram* can provide insight on extremal dependence between components in a multivariate time series.

• Extensions to spatial and space-time domains are possible.

• Theory for the *extremogram* has been developed for spatial data that are observed at *unequal spaced locations*.