

Air
Land
Sea
Space
Cyberspace

Innovation. In all domains.

Building Requirements-Flow Models using Bayesian Networks and Designed Simulation Experiments

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Outline

- **Background & Motivation**
 - The power of probability models
 - Requirements-flow models for subsystem requirements
- **Basics of Bayesian Networks and the synergy between BNs and Design & Analysis of Simulation Experiments (DASE)**
 - Examples: Rain-Sprinkler-Grass & Chair-Backache BNs
 - DASE terminology in context of BNs
- **Example Requirements-Flow Model: Weapon Kill-Chain**
 - Improving performance vs. a prior, similar system
 - Using inference engine and DASE to verify solution
- **Summary & Conclusions**

Harnessing the power of probability

- **E.T. Jaynes** (*Probability Theory: The Logic of Science*, Cambridge, 2003)

“The mathematical rules of probability theory are not merely rules for calculating frequencies of ‘random variables’; they are also the unique consistent rules for conducting inference (i.e. plausible reasoning).”
- **Definition of conditional probability:**
$$\Pr(A | B) = \frac{\Pr(A, B)}{\Pr(B)}$$

Numerator is the joint probability of (simple or compound) events A & B , and denominator is the marginal probability of “evidence event” B
- **Typical process for deriving subsystem requirements**

 - Ad-hoc quantitative & graphical methods are used to derive “flow-down” requirements
 - When compliance problems occur, issues arise when referring to artifacts of these methods (e.g., confusion between expressions of joint, conditional, and marginal probabilities)

Challenge: To create a logically consistent, probabilistic requirements-flow model

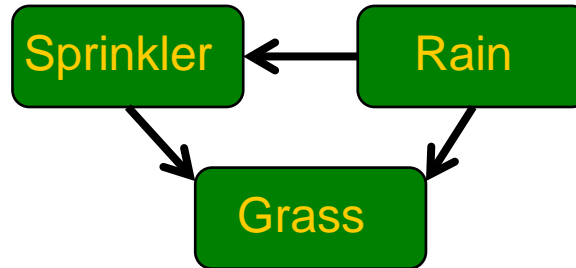
Example 1 (http://en.wikipedia.org/wiki/Bayesian_network)

Wet Grass, **G**; Sprinkler On **S**, & Raining, **R**

CPT_S (1 parent)

R	S	
	F	T
F	0.6	0.4
T	0.99	0.01

causally directed acyclic graph (DAG)



CPT_R (0 parents)

R	
F	T
0.8	0.2

Conditional Probability Tables (CPTs)

- Represent nodal events using discrete probability distributions
- Cells populated using data or best-guesses

CPT_G (2 parents)

R	S	G	
		F	T
F	F	1	0
T	F	0.2	0.8
F	T	0.1	0.9
T	T	0.01	0.99

Using rules of probability (e.g., JPD factorization, Law of Total Probability, & Bayes' Rule), a BN model is sufficient for computing correct probabilistic answers to specific questions.

Example 1 (G, S, R), Cont.: Computation for a specific query

Q1: What is the probability that it's raining, given that the grass is wet?

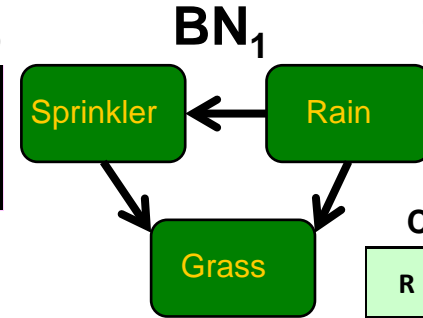
Start with conditional probability formula, and sum over "nuisance" variable(s) X :

$$\Pr(R | G) = \frac{\Pr(G, R)}{\Pr(G)} = \frac{\sum_{X \in \{S, !S\} \leftarrow 2^1 = 2 \text{ products}} \Pr(G, X, R)}{\sum_{X_1 \in \{S, !S\} \leftarrow 2^2 = 4 \text{ products}} \Pr(G, X_1, X_2)}$$

!X is the complement of X, i.e. 1 - X

CPT_S (1 parent)

R	S	
	F	T
F	0.6	0.4
T	0.99	0.01



CPT_R (0 parents)

R	
F	T
0.8	0.2

CPT_R (2 parents)

R	S	G	
		F	T
F	F	1	0
T	F	0.2	0.8
F	T	0.1	0.9
T	T	0.01	0.99

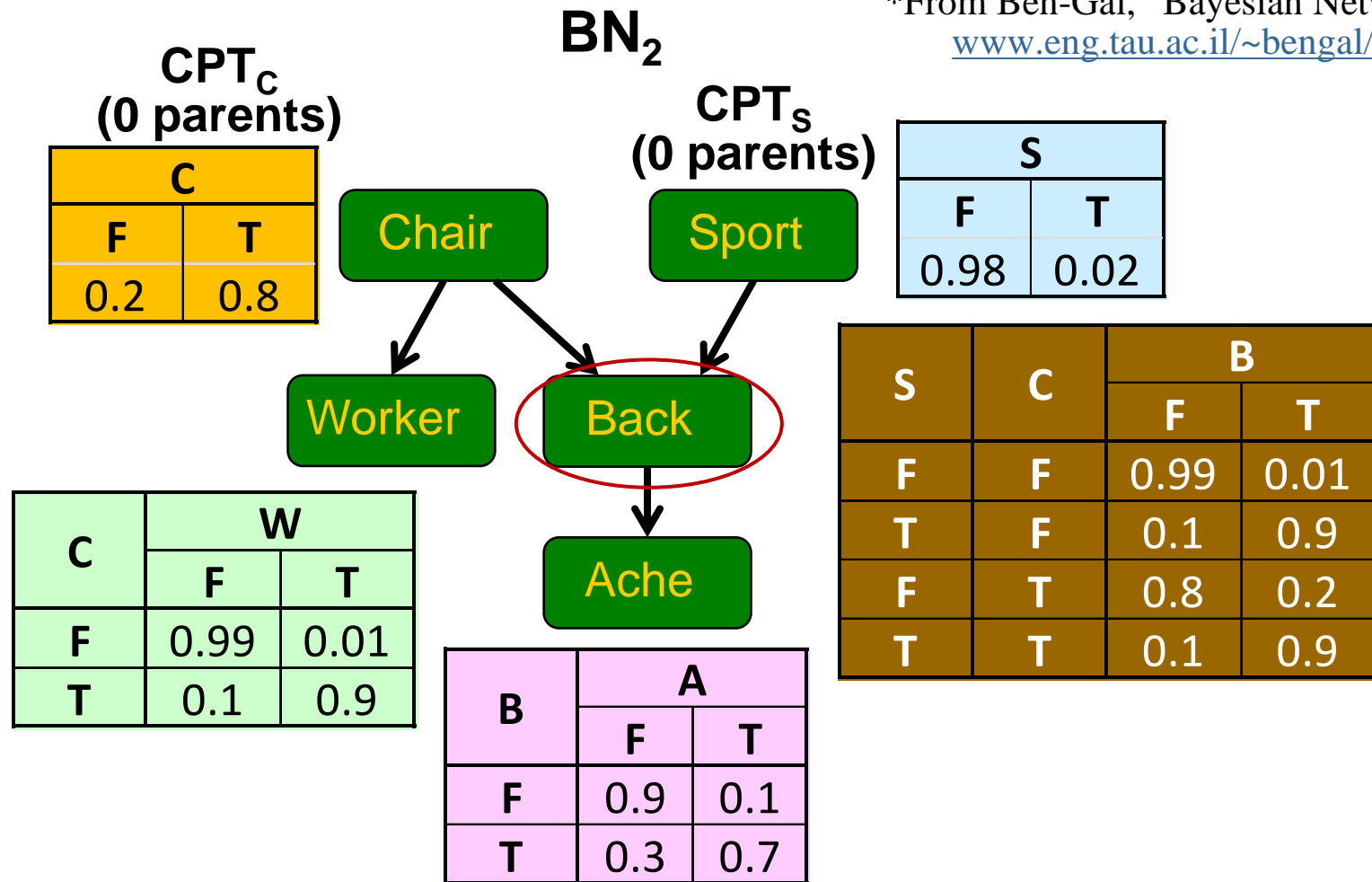
$$= \frac{\Pr(G | S, R) \Pr(S | R) \Pr(R) + \Pr(G | !S, R) \Pr(!S | R) \Pr(R)}{\Pr(G | S, R) \Pr(S | R) \Pr(R) + \Pr(G | S, !R) \Pr(S | !R) \Pr(!R) + \Pr(G | !S, R) \Pr(!S | R) \Pr(R) + \Pr(G | !S, !R) \Pr(!S | !R) \Pr(!R)}$$

$$= \frac{(0.99 \times 0.01 \times 0.2) + (0.8 \times 0.99 \times 0.2)}{(0.99 \times 0.01 \times 0.2) + (0.9 \times 0.4 \times 0.8) + (0.8 \times 0.99 \times 0.2) + (0 \times 0.6 \times 0.8)} = \frac{0.16038}{0.44838} = 0.358$$

∴ A1: The probability that it's raining, given wet grass, is ~36%.

Example 2*: Aching Back, **A**; Injury, **B**; Other Worker(s), **W**; Sports Injury, **S**; & Bad Chair, **C**

*From Ben-Gal, "Bayesian Networks," www.eng.tau.ac.il/~bengal/BN.pdf



Q2: What is the probability that Bob's chair is bad, given that his back aches?

Example 2 (A,B,W,S,C), cont.: Computation for specific question

Q2: What is the probability that Bob's chair is bad, given that his back aches?

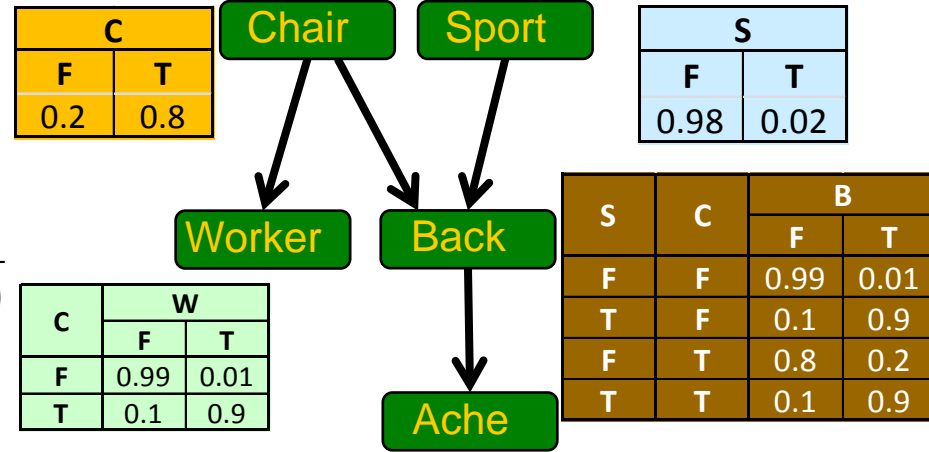
$$\Pr(C | A) = \frac{\Pr(A, C)}{\Pr(A)} = \frac{\sum_{\substack{X_1 \in \{B, !B\} \\ X_2 \in \{W, !W\} \\ X_3 \in \{S, !S\}}} \Pr(A, X_1, X_2, X_3, C)}{\sum_{\substack{X_1 \in \{B, !B\} \\ X_2 \in \{W, !W\} \\ X_3 \in \{S, !S\} \\ X_4 \in \{C, !C\}}} \Pr(A, X_1, X_2, X_3, X_4)}$$

← 2³ = 8 products

← 2⁴ = 16 products

Omit "Pr" to save space

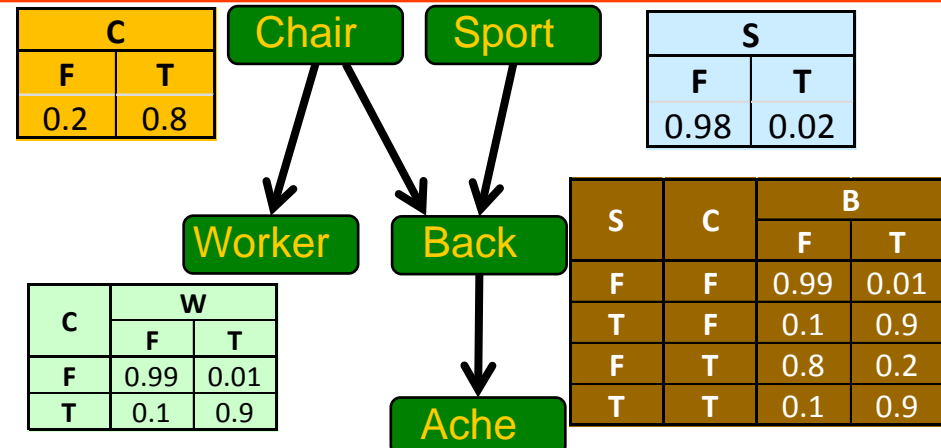
$$\begin{aligned} & \Rightarrow (A|B)(B|S,C)(W|C)(S)(C) + (A|B)(B|!S,C)(W|C)(!S)(C) \\ & + (A|B)(B|S,C)(!W|C)(S)(C) + (A|B)(B|C)(!W|C)(!S)(C) \\ & + (A|!B)(!B|S,C)(W|C)(S)(C) + (A|!B)(!B|C)(W|C)(!S)(C) \\ & + (A|!B)(!B|S,C)(!W|C)(S)(C) + (A|!B)(!B|C)(!W|C)(!S)(C) \\ & = \frac{\text{Num}}{\text{Den}} \end{aligned}$$



Example 2, cont.: Numerator Computation

$$\Pr(C | A) = \frac{\Pr(A, C)}{\Pr(A)} = \frac{\sum_{\substack{X_1 \in \{B, !B\} \\ X_2 \in \{W, !W\} \\ X_3 \in \{S, !S\}}} \Pr(A, X_1, X_2, X_3, C)}{\sum_{\substack{X_1 \in \{B, !B\} \\ X_2 \in \{W, !W\} \\ X_3 \in \{S, !S\} \\ X_4 \in \{C, !C\}}} \Pr(A, X_1, X_2, X_3, X_4)}$$

$\leftarrow 2^3 = 8 \text{ products}$
 $\leftarrow 2^4 = 16 \text{ products}$



$$\left(\begin{aligned} & (A|B)(B|S,C)(W|C)(S)(C) + (A|B)(B|!S,C)(W|C)(!S)(C) \\ & 0.7 \times 0.9 \times 0.9 \times 0.02 \times 0.8 + 0.7 \times 0.2 \times 0.9 \times 0.98 \times 0.8 \\ & + (A|B)(B|S,C)(!W|C)(S)(C) + (A|B)(B|!S,C)(!W|C)(!S)(C) \\ & 0.7 \times 0.9 \times 0.1 \times 0.02 \times 0.8 + 0.7 \times 0.2 \times 0.1 \times 0.98 \times 0.8 \\ & + (A|!B)(!B|S,C)(W|C)(S)(C) + (A|!B)(!B|!S,C)(W|C)(!S)(C) \\ & 0.1 \times 0.1 \times 0.9 \times 0.02 \times 0.8 + 0.1 \times 0.8 \times 0.9 \times 0.98 \times 0.8 \\ & + (A|!B)(!B|S,C)(!W|C)(S)(C) + (A|!B)(!B|!S,C)(!W|C)(!S)(C) \\ & 0.1 \times 0.1 \times 0.1 \times 0.02 \times 0.8 + 0.1 \times 0.8 \times 0.1 \times 0.98 \times 0.8 \end{aligned} \right) = 0.1827$$

Example 2, cont.: Denominator computation

As the number of nodes k and the number of states per node m increase, the computational complexity for a general joint probability distribution grows as $O(m^k)$; with BNs, it grows more slowly, as square of the maximum number of parents per node.

$$\begin{aligned}
 & (A|B)(B|S,C)(W|C)(S)(C) + (A|B)(B|S,!C)(W|!C)(S)(!C) \\
 & \quad 0.7 \times 0.9 \times 0.9 \times 0.02 \times 0.8 + 0.7 \times 0.9 \times 0.01 \times 0.02 \times 0.2 \\
 & + (A|B)(B|!S,C)(W|C)(!S)(C) + (A|B)(B|!S,!C)(W|!C)(!S)(!C) \\
 & \quad 0.7 \times 0.2 \times 0.9 \times 0.98 \times 0.8 + 0.7 \times 0.01 \times 0.01 \times 0.98 \times 0.2 \\
 & + (A|B)(B|S,C)(!W|C)(S)(C) + (A|B)(B|S,!C)(!W|!C)(S)(!C) \\
 & \quad 0.7 \times 0.9 \times 0.1 \times 0.02 \times 0.8 + 0.7 \times 0.9 \times 0.99 \times 0.02 \times 0.2 \\
 & + (A|B)(B|!S,C)(!W|C)(!S)(C) + (A|B)(B|!S,!C)(!W|!C)(!S)(!C) \\
 & \quad 0.7 \times 0.2 \times 0.1 \times 0.98 \times 0.8 + 0.7 \times 0.01 \times 0.99 \times 0.98 \times 0.2 \\
 & + (A|!B)(!B|S,C)(W|C)(S)(C) + (A|!B)(!B|S,!C)(W|!C)(S)(!C) \\
 & \quad 0.1 \times 0.1 \times 0.9 \times 0.02 \times 0.8 + 0.1 \times 0.1 \times 0.01 \times 0.02 \times 0.2 \\
 & + (A|!B)(!B|!S,C)(W|C)(!S)(C) + (A|!B)(!B|!S,!C)(W|!C)(!S)(!C) \\
 & \quad 0.1 \times 0.8 \times 0.9 \times 0.98 \times 0.8 + 0.1 \times 0.99 \times 0.01 \times 0.98 \times 0.2 \\
 & + (A|!B)(!B|S,C)(!W|C)(S)(C) + (A|!B)(!B|S,!C)(!W|!C)(S)(!C) \\
 & \quad 0.1 \times 0.1 \times 0.1 \times 0.02 \times 0.8 + 0.1 \times 0.1 \times 0.99 \times 0.02 \times 0.2 \\
 & + (A|!B)(!B|!S,C)(!W|C)(!S)(C) + (A|!B)(!B|!S,!C)(!W|!C)(!S)(!C) \\
 & \quad 0.1 \times 0.8 \times 0.1 \times 0.98 \times 0.8 + 0.1 \times 0.99 \times 0.99 \times 0.98 \times 0.2
 \end{aligned}$$

= 0.2061

Example 2 (A,B,W,C,S), cont.

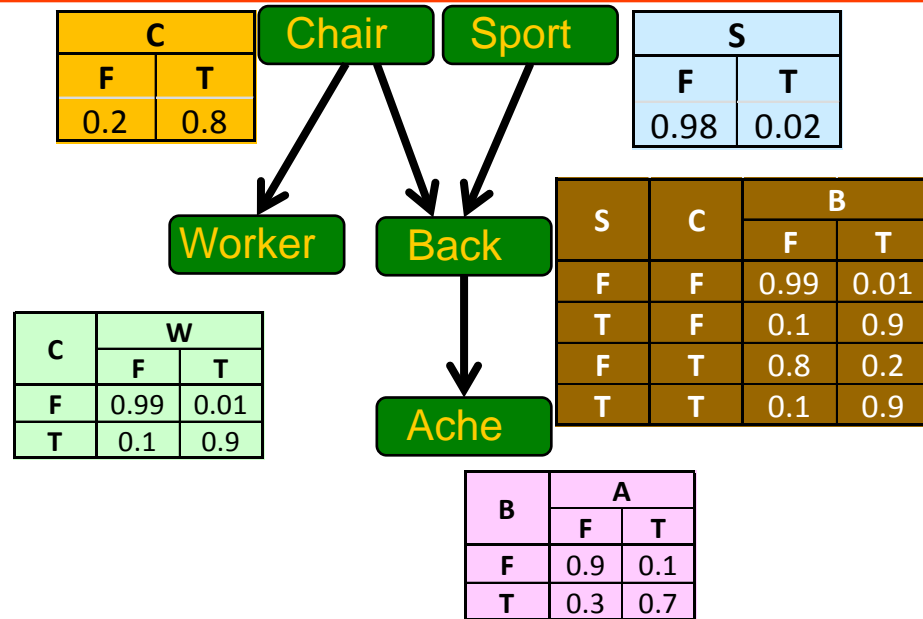
Computation for specific question

A2: The probability that Bob's chair is bad, given that his back aches is

$$\Pr(C | A) = \frac{\Pr(A, C)}{\Pr(A)} = \frac{\sum_{\substack{X_1 \in \{B, !B\} \\ X_2 \in \{W, !W\} \\ X_3 \in \{S, !S\}}} \Pr(A, X_1, X_2, X_3, C)}{\sum_{\substack{X_1 \in \{B, !B\} \\ X_2 \in \{W, !W\} \\ X_3 \in \{S, !S\} \\ X_4 \in \{C, !C\}}} \Pr(A, X_1, X_2, X_3, X_4)}$$

$\leftarrow 2^3 = 8 \text{ products}$
 $\leftarrow 2^4 = 16 \text{ products}$

$$= \frac{0.1827}{0.2061} = 0.8867$$

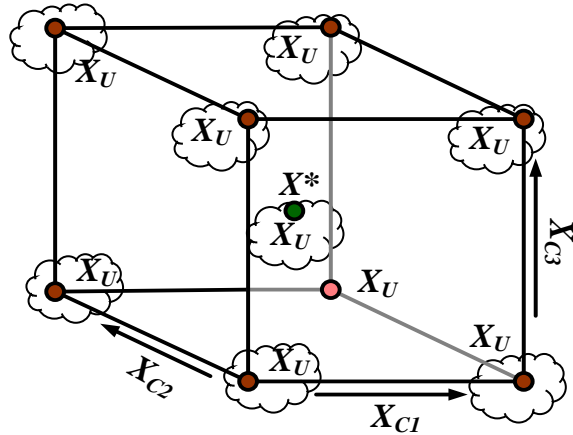


∴ A2: The probability that Bob's chair is bad, given that his back aches, is ~89%.

As demonstrated on previous slides, we definitely need software (*inference engine*) to do these computations correctly, given a valid model (BN + nodal state definitions + CPTs). Examples: Kevin Murphy's Bayes Net Toolbox: <http://code.google.com/p/bnt/> & UCLA's Samlam: <http://reasoning.cs.ucla.edu/samiam/>

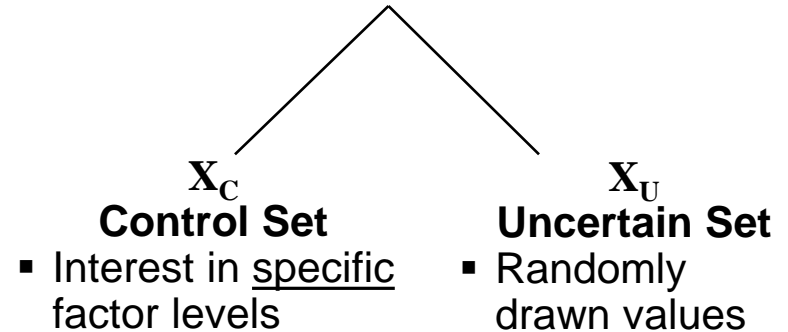
Synergy of DASE, Design & Analysis of Simulation Experiments, with BNs

The Factor Hypercube*



At each chosen point in the \mathbf{X}_C space, a set of random draws from factor set \mathbf{X}_U is made.

Factor-Set Assignment



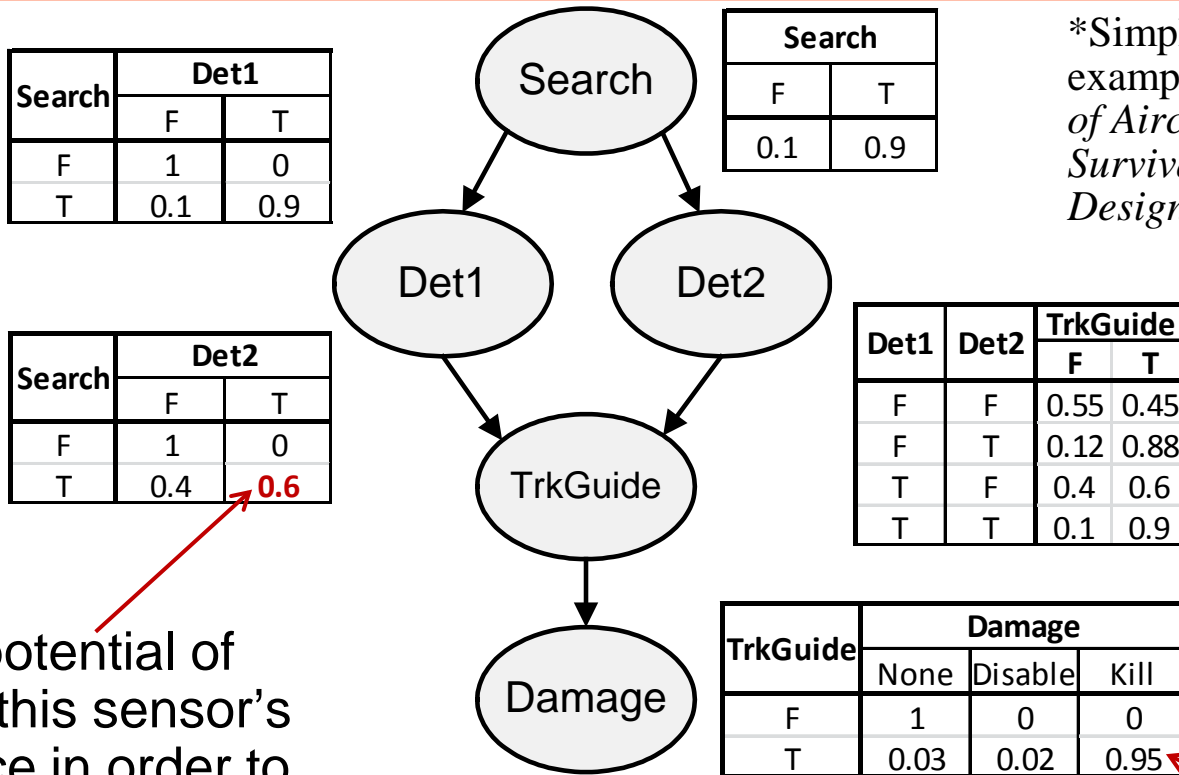
*The most common DASE experimental design is space-filling, i.e. Latin Hypercube Sampling, to obtain response *summary statistics*, which—in the case of BNs—are used to populate CPT entries.

DASE is used in the 1st and 3rd stages of requirements-flow modeling:

- 1) Populate BN's CPT entries with baseline sample proportion estimates
- 2) “Judiciously” modify baseline CPT entries, weighing cost/benefit options
- 3) Verify that new design satisfies the BN's modified CPT entries and system performance requirements, which are stated as marginal probabilities

Example 3*

Weapon kill-chain model for anti-aircraft missile



*Simplified from Ball's example in *The Fundamentals of Aircraft Combat Survivability Analysis & Design* (2nd ed., 2003)

Observe the higher conditional potential of Sensor2 vs. Sensor1.²

Exploring potential of increasing this sensor's performance in order to increase P_K^1 value from baseline system's 0.70 to new system's 0.77

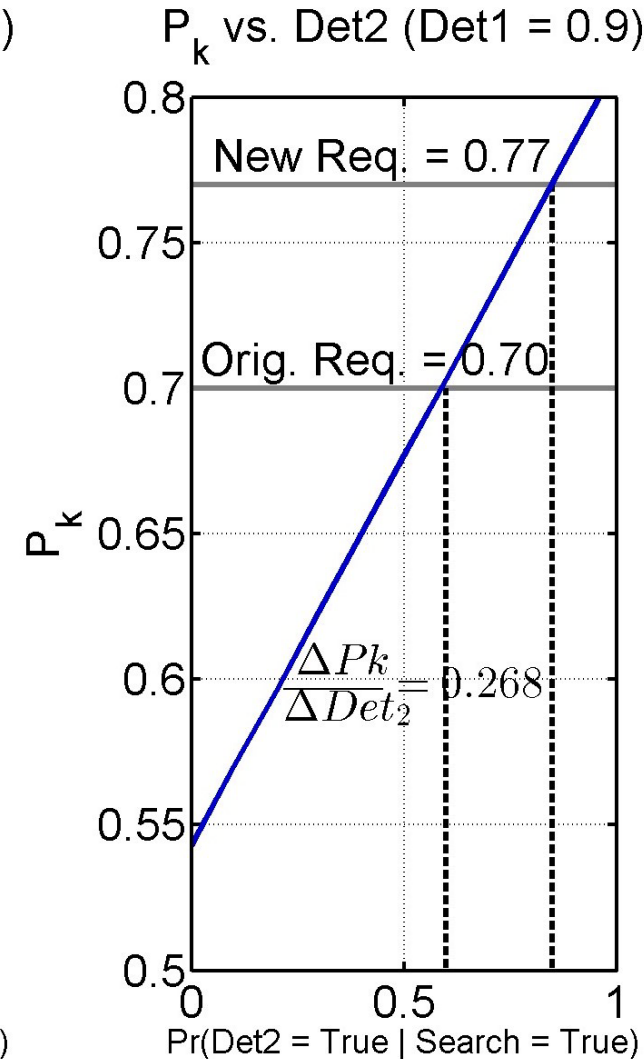
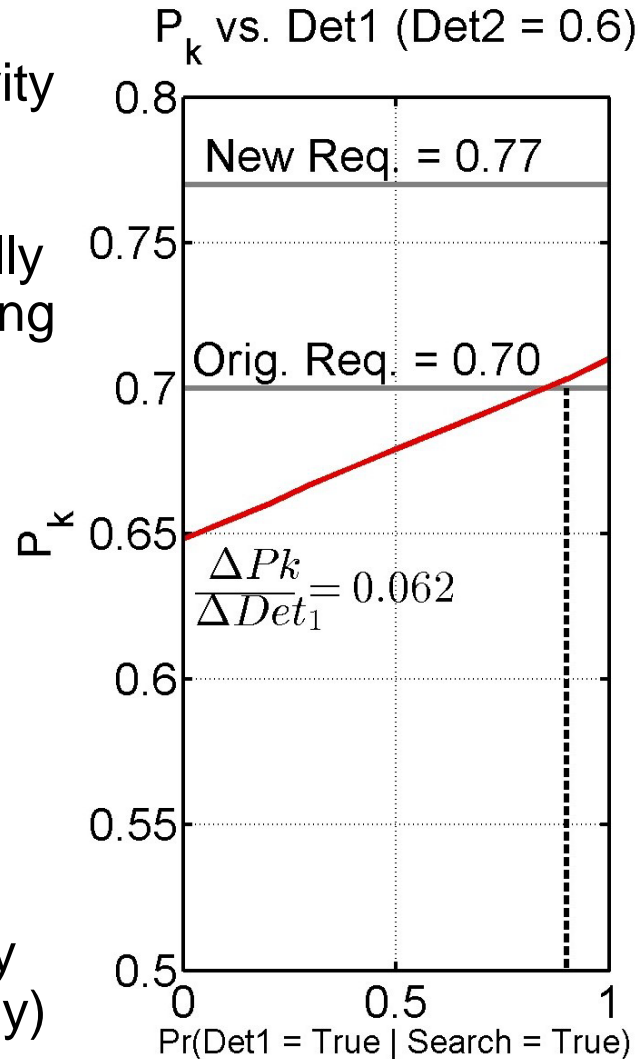
¹Common error: to confuse a conditional probability like $Pr(Damage=Kill / TrkGuide = True)$, with a marginal probability like P_K

²We're ignoring potential for improving both sensors' performance simultaneously—along with many more complex, allowable queries of this BN!

Sensitivity Analysis

Weapon kill-chain model for anti-aircraft missile

- Simple, 1-factor sensitivity queries for each sensor quantify the higher potential for incrementally improving P_K by improving Sensor2's performance than Sensor1's
- In addition, Sensor1's performance is already closer to 1; incremental improvements are likely more difficult to obtain
- Therefore, the better decision is to improve Sensor2 (and then verify with another DASE study)



Many, more-complex queries can be explored using the same BN.



Summary

- **Combined with DASE, Bayesian networks (BNs) provide a way to allocate & evaluate subsystem requirements in a quantitative, comprehensive manner**
 - A rigorous probability model enables immediate evaluation of “what-if” queries when considering subsystem improvements
 - A requirements-flow model enables immediate sensitivity analysis and upper-bound estimates on the likely achievable gains of a proposed improvement
 - BNs provide a natural framework for integrating results from multiple DASE studies to mitigate suboptimization
- **Many tools exist for DASE and BN development**

The challenge: To educate engineers in the promise of BNs + DASE and the use of available tools.