# Mixing Apples and Oranges: Complex System Reliability Estimation with Mixed Modal Testing An Application to Defense Missile Systems

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# Outline



### Problem Introduction



- **Hierarchical Models** 
  - Likelihood Specification
  - Likelihood Functions for Data
  - Prior Models
    - Reparameterized Beta Distributions
    - Uniform Priors: Component or System?
    - Historical Data and Commensurate Priors
- Defense System Application
  - Data
  - Additional Likelihood Contribution
  - Application Prior Information
  - Posterior Results
- 5 Conclusions and Suggestions for Future Work

### **Problem Introduction**

Defense systems must meet specified reliability requirements for aquisition.



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- Goal: Assess reliability with limited test resources.

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- Problem: data sources are diverse and available at various different levels.

## 2 Example Systems

• System 1:



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- Challenge: data sources are diverse and available at various different levels.

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- System flight (destructive) testing, Y<sub>D</sub>

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## **Resulting Distributions**

• Output of data sources are diverse:



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  - **1** Probability distributions:  $Y_{SME}$ ,  $Y_{CM}$
  - 2 Binary Data:  $Y_C$ ,  $Y_{NDE}$ ,  $Y_D$
  - Lifetime Data (complete or censored): Y<sub>C</sub>, Y<sub>NDE</sub>, Y<sub>D</sub>



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  - Degradation Data: Y<sub>CM</sub>, Y<sub>C</sub>, Y<sub>NDE</sub>

### How to Incorporate?

• Many sources, many choices

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- Bayesian approach: all sources allowed to inform the posterior.
- Question to be considered: Should all sources impact assessment?

Problem Introduction Data Sources Hierarchical Models Defense System Application

Conclusions and Suggestions for Future Work

## A Simple System

Likelihood Specification Likelihood Functions for Data Prior Models



Reese Mixing Apples and Oranges: Complex System Reliability Estimation

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  - Data Sources
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### Basic (but important) Notions for this talk

• Operational definition of reliability:

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  - System reliability is the probability of a system to perform a required function under stated conditions for a specified period of time

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- "Specified period of time": mission time t\*

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- "Specified period of time": mission time t\*
- Bayesian Modeling

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# Fundamentals of Bayesian Modeling

Bayesian Data Analysis

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# Fundamentals of Bayesian Modeling

- Bayesian Data Analysis
  - data (enters through the likelihood function as well as allowance of other information

$$p(\theta|y_1,\ldots,y_n) = \frac{\prod_{i=1}^n f(y_i|\theta) \times \pi(\theta)}{\int \prod_{i=1}^n f(y_i|\theta) \times \pi(\theta) d\theta}$$

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Likelihood Specification

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- - reads: the *posterior distribution* [ $p(\theta|y_1, \ldots, y_n)$ ] is a constant multiplied by the likelihood  $[\prod_{i=1}^{n} f(y_i | \theta)]$  muliplied by the prior distribution  $[\pi(\theta)]$

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- **2** reads: the *posterior distribution*  $[p(\theta|y_1,...,y_n)]$  is a constant multiplied by the likelihood  $[\prod_{i=1}^n f(y_i|\theta)]$  muliplied by the *prior distribution*  $[\pi(\theta)]$
- opsterior distribution: in light of the data our updated view of the reliabilities of components of a system
- Prior distribution: before any data collection, the view of the reliabilities (e.g., expert opinion, historical data, data on similar systems)

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Likelihood Specification Likelihood Functions for Data Prior Models

### **Basic Tenants of this Talk**

Define the likelihood function (distribution of the various data sources)

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Likelihood Specification Likelihood Functions for Data Prior Models

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  - 2 Uniform prior distributions at various levels

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Model for System Likelihood

• Likelihood for SYSTEM LEVEL DATA (*y*<sub>S</sub>): Lifetime, Vibration, etc.

$$f_{\mathcal{S}}(y_{\mathcal{S}}|\Theta) = \prod_{k=1}^{n_{\mathcal{S}}} \sum_{i=2}^{4} f_{i}(y_{\mathcal{S}_{k}}|\Theta_{i}) \prod_{j \neq i} (R(y_{\mathcal{S}_{k}}|\Theta)).$$

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- $n_S$  is the number of system tests
- Derived from distribution of minimum.
- Above representation is for series systems (similar representations available for parallel systems)

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# Model for Component Likelihood

 Likelihood for SYSTEM LEVEL DATA (x<sub>S</sub>, n<sub>S</sub>): Pass/Fail (Series)

$$g_{S}(x_{S}|R_{i}(t*)) \propto (\prod_{i=1}^{n_{C}} R_{i}(t*))^{x_{S}}(1 - \prod_{i=1}^{n_{C}} R_{i}(t*))^{n_{S}-x_{S}}$$

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- Incorrectly specified system structures have huge impact.

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### Model for Component Likelihood

#### • Likelihood for COMPONENT LEVEL DATA $(y_{C_i})$

$$f_{C_i}(y_{C_i}|\Theta_i) = \prod_{k=1}^{n_i} f_i(y_{C_{ik}}|\Theta_i), \qquad i = 1, n_c$$

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 Note: In theory, the likelihoods for the different components may be different.

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- Note: In theory, the likelihoods for the different components may be different.
- Model checking advised!

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## Model for Component Likelihood

 Likelihood for COMPONENT LEVEL DATA (x<sub>Ci</sub>, n<sub>Ci</sub>): Pass/Fail

$$g_{C_i}(x_{C_i}|R_i(t^*)) \propto R_i(t^*)^{x_{C_i}}(1-R_i(t^*))^{n_i-x_{C_i}}, \qquad i=1, n_c$$

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Likelihood Specification Likelihood Functions for Data Prior Models

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- Likelihood composed of sequences of Bernoulli trials.

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# Full Likelihood Model

$$\begin{split} f(y_{FULL}|\Theta, R(t)) &= g_{\mathcal{S}}(y_{\mathcal{S}}|R(t*)) \times \prod_{i=1}^{n_{\mathcal{C}}} g_{\mathcal{C}_i}(y_{\mathcal{C}_i}|R_i(t*)) \\ &\times f_{\mathcal{S}}(y_{\mathcal{S}}|\Theta) \times \prod_{i=1}^{n_c} f_{\mathcal{C}_i}(y_{\mathcal{C}_i}|\Theta_i) \end{split}$$

where  $y_{FULL} = (y_S, y_{C_i}, x_S, n_s, x_{C_i}, n_{C_i}), \quad i = 1, ..., n_c.$ 

• Aggregation complications are avoided via substitution.

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### **Extensions to Censoring**

Censoring Type	Likelihood Contribution
Uncensored	$f_i(t \theta)$
Right Censored( $t > t_R$ )	$1 - F_i(t_R \theta)$
Left Censored( $t < t_L$ )	$F_i(t_L \theta)$
Interval Censored( $t_L \leq t \leq t_R$ )	$F_i(t_R \theta) - F_i(t_L \theta)$

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# Hierarchical Models

- Likelihood Specification
- Likelihood Functions for Data

#### Prior Models

- Reparameterized Beta Distributions
- Uniform Priors: Component or System?
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# **Reparameterized Beta Distributions**

 Experts often have an easier time specifying component reliability (π<sub>i</sub>) and an associated *weight* or *worth* (η<sub>i</sub>)

$$p(R_i) ~\propto~ R_i^{\pi_i\eta_i-1}(1-R_i)^{(1-\pi_i)\eta_i-1}$$

where  $R_i$  is the unknown component reliability,  $\pi_i$  is the SME specified reliability and  $\eta_i$  is the equivalent "worth" or "weight" of the SME experience.

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where  $R_i$  is the unknown component reliability,  $\pi_i$  is the SME specified reliability and  $\eta_i$  is the equivalent "worth" or "weight" of the SME experience.

• Example: Suppose a SME estimates the reliability to be 0.80 and additional SME's "value" her opinion as 8 component tests. Then, the prior would be specified as  $\pi_i = 0.80$  and  $\eta_i = 8$ .

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### **Reparameterized Beta Distributions**

• More commonly is that the value of  $\eta_i$  is *uncertain*.

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# **Reparameterized Beta Distributions**

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# **Reparameterized Beta Distributions**

- More commonly is that the value of  $\eta_i$  is *uncertain*.
- Solution: A prior on the prior distribution for the value of the weight of the SME specified reliability.
- Hierarchical Prior:

- $\alpha \sim Gamma(a_{\alpha}, b_{\alpha})$
- $\beta \sim Gamma(a_{\beta}, b_{\beta})$

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Likelihood Specification Likelihood Functions for Data Prior Models

### A Note on Uniform Priors

• Series system of *n<sub>c</sub>* components

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### A Note on Uniform Priors

- Series system of *n<sub>c</sub>* components
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- Equal allocation of failure probabilities

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### A Note on Uniform Priors

- Series system of *n<sub>c</sub>* components
- Uniform system prior
- Equal allocation of failure probabilities
- Component Priors

$$\pi_{i}\eta_{i} = \frac{(2/3)^{1/n_{c}} - 1}{1 - (4/3)^{1/n_{c}}}$$
$$(1 - \pi_{i})\eta_{i} = \pi_{i}\eta_{i}\frac{1 - (1/2)^{1/n_{c}}}{(1/2)^{1/n_{c}}} = \left(\frac{(2/3)^{1/n_{c}} - 1}{1 - (4/3)^{1/n_{c}}}\right) \left(\frac{1 - (1/2)^{1/n_{c}}}{(1/2)^{1/n_{c}}}\right)$$

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#### A Note on Uniform Priors

number of components	$\eta_i \pi_i$	$\eta_i(1 - \pi_i)$
1	1.00	1.00
2	1.19	0.49
3	1.26	0.33
7	1.34	0.14
8	1.35	0.12

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Graphical Illustration on Uniform Priors ( $n_c = 2$ )



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Mixing Apples and Oranges: Complex System Reliability Estimati

Prior Models

### <u>Graphical Illustration on Uniform Priors ( $n_c = 2$ )</u>



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Graphical Illustration on Uniform Priors ( $n_c = 7$ )



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### Graphical Illustration on Uniform Priors ( $n_c = 7$ )



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Likelihood Specification Likelihood Functions for Data Prior Models

### Incorporation of Historical Data: Commensurate Priors

 Hobbs et al. (2011) offers an adaptive approach for incorporating historical data

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Likelihood Specification Likelihood Functions for Data Prior Models

### Incorporation of Historical Data: Commensurate Priors

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- Let  $D_0$  be historical data with likelihood  $L(D_0|\theta_0)$ .

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- Also, assume a vague initial prior for θ (either reliabilities, or parameters governing the reliability distribution), π<sub>0</sub>(θ).

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Likelihood Specification Likelihood Functions for Data Prior Models

## Incorporation of Historical Data: Commensurate Priors

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- Let  $D_0$  be historical data with likelihood  $L(D_0|\theta_0)$ .
- Also, assume a vague initial prior for  $\theta$  (either reliabilities, or parameters governing the reliability distribution),  $\pi_0(\theta)$ .
- Then, we can obtain the posterior distribution of θ through a hierarchical distributional specification:

$$\pi(\theta|D_0, \theta_0, \tau) \propto L(D_0|\theta_0)\pi(\theta|\theta_0, \tau)\pi_0(\theta)$$

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Likelihood Specification Likelihood Functions for Data Prior Models

### Commensurability Parameter, $\tau$

$$\pi(\theta|D_0, \theta_0, \tau) \propto L(D_0|\theta_0)\pi(\theta|\theta_0, \tau)\pi_0(\theta)$$

*τ* governs commensurability between historical and current data.

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### Commensurability Parameter, $\tau$

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### Commensurability Parameter, $\tau$

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- *τ* governs commensurability between historical and current data.
  - $\tau \longrightarrow 0$  implies high discordance, and historical data are effectively ignored
  - 2  $\tau \longrightarrow \infty$  implies high commensurability ( $\theta \equiv \theta_0$ ), and historical data are pooled as equal partners in posterior estimation.

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    - Reparameterized Beta Distributions
    - Uniform Priors: Component or System?
    - Historical Data and Commensurate Priors
- Defense System Application

#### Data

- Additional Likelihood Contribution
- Application Prior Information
- Posterior Results
- 5) Conclusions and Suggestions for Future, Work, ,

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### Flight Test Data

Component	Tests	Failures
System	3	0
1	12	1
2	14	1
3	49	1
4	64	0
5	36	1
6	20	1
7	7	0

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## **Missile Likelihood**

 Limited (3-5) number of component tests incorporated sensors on several components to determine vibration impacts on reliability.

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# **Missile Likelihood**

- Limited (3-5) number of component tests incorporated sensors on several components to determine vibration impacts on reliability.
- Likelihood: Assume that the distribution of component failure times (all but one was censored) of the are Weibull, that is

$$f_i(\mathbf{v}) = \frac{\alpha_i}{\beta_i} \left( \mathbf{v}/\beta_i \right)^{\alpha_i} \exp\left[-\left(t/\beta_i\right)^{\alpha_i}\right], \qquad i = 2, 3, 4$$

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 where ν is the vibration until failure, and α and β are the shape and scale parameters of the Weibull distributions.

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### **Prior Specification**

#### • Uniform prior:

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3	1.26	0.33
7	1.34	0.14
8	1.35	0.12

Borrowing from other systems using reparameterized Beta

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### **Computation: MCMC**

Standard Successive Substitution Algorithm

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### **Computation: MCMC**

- Standard Successive Substitution Algorithm
- Updates on logit scale accommodate very high (and very low!) reliabilities

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- Updates on logit scale accommodate very high (and very low!) reliabilities
- Based on 1,000,000 draws from the full posterior

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### **Computation: MCMC**

- Standard Successive Substitution Algorithm
- Updates on logit scale accommodate very high (and very low!) reliabilities
- Based on 1,000,000 draws from the full posterior
- No adaptation. Posterior may not be amenable. (Rosenthal, 2008)

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## System Reliability



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#### Reliability with all data incorporated



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#### Comparison of Reliability Contribution



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#### **Issues for Future Work**

 Inclusion of repairable systems (maintenance, replacement of parts, etc.)

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#### **Issues for Future Work**

- Inclusion of repairable systems (maintenance, replacement of parts, etc.)
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- Inclusion of repairable systems (maintenance, replacement of parts, etc.)
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- Incorporation of accelerated life test data (excluded in current modeling)

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## **Issues for Future Work**

- Inclusion of repairable systems (maintenance, replacement of parts, etc.)
- Use of actual computer modeling in construction of prior distributions
- Incorporation of accelerated life test data (excluded in current modeling)
- Nonparametric bayes does not assume rigid, parametric forms, but may require datasets that are too large for realistic implementation.

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 Multiple test modalities can be accomplished (!), but it requires modification of likelihood and innovative use of prior distributions

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- Multiple test modalities can be accomplished (!), but it requires modification of likelihood and innovative use of prior distributions
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  - Biological systems?

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- System structure diagram must be accurate (how to relax this?)
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  - Biological systems?
  - Output Survey sampling come to the clinical session!

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